

TSC – Triple Space Computing

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5 Triple Space Computing (TSC) has been proposed as communication and coordination paradigm based on the convergence of space-
6 based computing and the Semantic Web. It acts as a global virtual shared space like middleware to enable communication and
7 coordination of semantic data based on the principle of publish and read. This paper presents an overview of the work in progress under
8 Austrian FIT-IT funded TSC project (<http://tsc.deri.at>). It presents the evolution of the TSC framework, overall architecture and its usage
9 by Semantic Web Services.

10 Keywords: communication; coordination; middleware; Semantic Web Services; space-based computing

11 TSC – Triple Space Computing.

12 *Triple Space Computing (TSC) ist ein neuartiges Kommunikations- und Koordinationsparadigma, welches aus einer Kombination von*
13 *„Tuple Spaces“ und Semantic Web-Technologien entstanden ist. Der global zugängliche virtuelle Space stellt eine Middleware zur*
14 *Verfügung, welche es ermöglicht, semantische Daten via Publizieren und Lesen auszutauschen. In diesem Artikel wird die Entstehung und*
15 *Entwicklung vom FIT-IT Projekt TSC (<http://tsc.deri.at>) vorgestellt: die Rahmenbedingungen und Datenmodelle, eine Architektur und*
16 *Anwendungsbeispiele im Zusammenhang mit Semantic Web Services.*

17 *Schlüsselwörter: Kommunikation; Koordination; Middleware; Semantic Web Services; Space-based Computing*

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21 1. Introduction

22 Aiming at enhancing the facilities for automated information processing on the Internet, Tim Berners-Lee (inventor of the World
23 Wide Web and Director of the W3C) brought up the vision of the Semantic Web. Since existing Web technologies around URI, HTTP,
24 and HTML do not support automated processing of Web content, the aim is to develop technologies that allow describing Web
25 content in a structured manner; furthermore, semantically defined meta-data shall help to overcome the problem of heterogeneity
26 within the Internet as an open and distributed system. Ontologies have been identified as the basic building block for the Semantic
27 Web, as they provide machine-processable, semantic terminology definitions.

28 In conjunction with the idea of the Semantic Web, Web Services are proposed as the technology for automated information processing,
29 thus combining the benefits of the Web with the strength of component-oriented computation. In fact, Web Services promise
30 to allow automated interaction and seamless integration of several entities of the Web, thus are considered as the technology for next
31 generation information systems with special regard to Enterprise Application Integration, B2B technologies, and e-commerce. As
32 initial Web Service technologies around SOAP, WSDL, and UDDI failed to realize the promise of seamless interoperability, the concept
33 of Semantic Web Services has been conceived. By adding semantics to Web Service descriptions, intelligent inference-based mechanisms
34 shall allow automated discovery, composition, and execution of Web Services.

35 Space-based computing has its roots in parallel processing. Linda was developed by David Gelernter in the mid-1980s at Yale University.
36 Initially presented as a partial language design (Gelernter, 1985), it was then recognized as a novel communication model on its
37 own and is now referred to as a coordination language for parallel and distributed programming. Coordination provides the infrastruc-
38 ture for establishing communication and synchronization between

39 activities and for spawning new activities. There are many instantiations or implementations of the Linda model, embedding Linda in
40 a concrete host language. Examples include C-Linda, Fortran-Linda and Shared-Prolog. Linda allows defining executions of activities or
41 processes orthogonal to the computation language, i.e. Linda does not care about, how processes do the computation, but only how
42 these processes are created. The Linda model is a memory model. The Linda memory is called tuple space and consists of logical tuples.
43 There are two kinds of tuples. Data tuples are passive and contain static data, process tuples or “live tuples” are active and represent
44 processes under execution. Processes exchange data by writing and reading data tuples to and from the tuple space.

45 In 2003 and 2004 there have been discussions and collaborations involving Tim Berners Lee, Dieter Fensel, Eva Kuehn and Frank
46 Leymann on the relationships between the Semantic Web, Web Services and space-based computing. Based on that, Dieter Fensel
47 published a technical report about “Triple Based Computing” presenting the idea of a semantically enabled, space-based communication
48 and coordination middleware as an infrastructure for the Semantic Web and Semantic Web Services. These ideas have
49 been adopted for the research project “Triple Space Computing” (TSC) funded by the Forschung, Innovation, Technologie – Informationstechnologie (FIT-IT) research programme in the
50 programme line of “semantic systems and services”. Triple Space Computing inherits the publication-based communication model
51 from the space-based computing paradigm and extends it with

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1 semantics. Instead of sending messages back and forth among partic-
 2 ipants as in current message-based technologies, TSC-enabled ap-
 3 plications will communicate by writing and reading RDF triples in the
 4 shared space.

5 2. Triple Space Computing framework

6 Triple Space Computing (TSC) (Fensel, 2004) implies a number
 7 of requirements that are not addressed in traditional Linda-like
 8 (Gelernter, 1985) systems. The requirements are depicted in
 9 Table 1. They are mainly concerned with enhancing tuple spaces
 10 with Web and Semantic Web technology like resource identification,
 11 Semantic Web data models (Resource Description Framework, RDF
 12 (Klyne, Carroll, 2004)) and query functionality (semantic matching).
 13 Moreover, TSC is expected to consider the extended scope of in-
 14 teraction – tuple spaces traditionally serve as communication plat-
 15 form for process and in-house coordination based on a limited
 16 number of servers, while TSC aims at a virtually global information
 17 space. This results in additional requirements on security, reliability
 18 and scalability.

19 With these requirements in mind, the TSC Framework defines
 20 the data models, matching algorithms, interaction APIs and security
 21 models at the convergence of space-based computing/shared
 22 object spaces and the Semantic Web. The former takes influence
 23 on the interaction patterns and data matching, while the latter
 24 determined in particular the RDF-based data modeling approach
 25 and the storage/query engine installation. In other words TSC
 26 borrowed from space-based computing its access primitives, trans-
 27 actional support and eventing/notification mechanism, while the
 28 Semantic Web provides the RDF triple syntax and semantics with
 29 the resource identification mechanism (URI) and vocabulary separa-
 30 tion mechanism (namespaces). Moreover, the RDF query lan-
 31 guages heavily influenced the definition of the matching mechanism
 32 through SPARQL (Prud'hommeaux, Seaborne, 2006) and N3QL
 33 (Berners-Lee, 2004) technology.

34 In the continuation of this section a closer look at the interaction
 35 API and semantic matching is given. First, however, we explain the
 36 core data model concepts.

37 The interaction API provides all the primitives defined in Linda. The
 38 operation names and functionality was, however, mainly influenced
 39 by more advanced commercial tuple space products like TSpaces
 40 (Lehmann, McLaughry, Wyckoff, 1999) and JavaSpaces (Freeman,
 41 Arnold, Hupfer, 1999). In short the API provides operations for
 42 writing, reading, removing in blocking and non-blocking manners.
 43 Moreover, convenience methods like update and count were also
 44 defined. More detailed descriptions of the different operations are
 45 given in Listing 1. Note that, in order to allow Web-like communica-
 46 tion, the traditional template-based read and take were enhanced
 47 with URI-based primitives that allow the extraction of information
 48 by identifier.

49 In addition to the core API shown in Listing 1 the TSC Framework
 50 provides APIs for the publish/subscribe extension, the definition of
 51 mediation rules, the management of spaces (creation, destruction),
 52 the handling of transaction (commit, rollback) and the definition of
 53 roles, permissions and users needed for the security framework. A
 54 user is associated with a particular role, while for every role and
 55 space the according access permissions can be set.

56 The semantic template matching mechanisms was motivated
 57 by recent achievement in RDF query languages. A template in Linda
 58 is a tuple where any of the tuple fields can be replaced by place-
 59 holders, so-called variables. In TSC templates are defined to be graph
 60 patterns (detailed definition in (Prud'hommeaux, Seaborne, 2006)).
 61 The graph patterns are RDF in Notation3 (N3, (Berners-Lee, 2001)),
 62 where variables can take the place of RDF nodes (cf. Listing 2).
 63 As graph patterns are at the basis of most RDF query languages
 64 (in particular SPARQL) the semantic templates can quite easily be
 65 transformed into queries according to the persistence framework
 66 (query engine) installed for the Triple Space (cf. Section 3). In that
 67 way the semantic templates of TSC provide a simple and extensible

Table 1. Triple Space Computing requirements

Web-like communication	Application and support of established Web technology like URI for resource identification, stateless exchange of information like supported by HTTP
Publishing mechanism	An interaction model based on the publication of information instead on the exchange of messages
Persistent storage	To ensure decoupling in time and in order to provide the 'publish and read'-paradigm the space must ensure persistency of data
Notification mechanism	For improved coordination and process flow decoupling the installation of a notification mechanism (publish-subscribe paradigm) is required
Search and query	Alignment of Linda-like template matching with Semantic Web query languages in order to provide semantic template matching
Trust and security	Any global information space must ensure confidentiality, integrity, non-repudiation and a trust mechanism to ensure a reasonable service middleware
Reliability	The requirement for persistency implies reliable recovery in case of system failure, as well as transactional support for atomic operations
Versioning	Access logging and tracing of changes is very important when sharing dynamic information in public spaces

Table 2. TSC data model concepts

Triple Space	A Triple Space is a uniquely addressable unit of the virtually global information space, i.e., every Triple Space has its own URI. The global space is built by an number of disjoint Triple Spaces (Fig. 1)
Triple	The data model of TSC inherits the syntax (Klyne, Carroll, 2004) and semantics (Hayes, McBride, 2004) of an RDF triple and the same definitions count
Graph	A graph (RDF graph) is defined in (Klyne, Carroll, 2004) as: An <i>RDF graph</i> is a set of RDF triples. Here too, TSC inherits the implied semantics
Named Graph	Named graphs (Carroll et al., 2005) are the fundamental data unit of TSC and as such all communication is based on named graphs. A named graph is a set of triples named by an URI, i.e. the pair (URI name, RDF graph g)

Listing 1. TSC Interaction API**write (URI ts, Transaction tx, Graph g): URI**

The write operation is used to publish an RDF graph to a triple space identified by the URI ts; the graph name is created by the space upon termination of the write operation and the data stored internally as named graph. Transactional write is supported

read (URI ts, Transaction tx, Template t): NamedGraph**take (URI ts, Transaction tx, Template t): NamedGraph****query (URI ts, Transaction tx, Template t): Graph**

These three template-based operations are applied to retrieve information from the space. Take has the same semantics as read (retrieval of an entire named graph), however, in a destructive manner. The query primitive on the other hand is used to aggregate all matching triples from the space ts independently of the associated RDF graph, thus it returns a new Graph instead of a whole NamedGraph object. Transactional interaction is supported here, too

read (URI ts, Transaction tx, URI n): NamedGraph**take (URI ts, Transaction tx, URI n): NamedGraph**

These two operations have the same semantics as their counterparts introduced above. However, they allow retrieving named graphs by use of their name (URI n)

waitToRead (URI ts, Transaction tx, Template t, TimeOut to): NamedGraph**waitToTake (URI ts, Transaction tx, Template t, TimeOut to): NamedGraph****waitToQuery (URI ts, Transaction tx, Template t, TimeOut to): Graph**

The waitTo-operations (the name was taken from TSpaces) provide blocking versions of the retrieval primitives.

While the previously introduced operations return with NULL in case no data was detected, the blocking versions wait until some match is detected or the timeout runs out. The semantics is otherwise precisely as above

update (URI ts, Transaction tx, NamedGraph ng): boolean

Update is on the one hand a convenience method for take and write, and on the other it ensures that graph names are only created by the space. Updates can only be done on graphs that are already known by name to the space. Here too, transactional update is supported

count (URI ts, Transaction tx, Template t): long

Count provides the exact same functionality as a loop with counter over a query operation. Note that count only provides an estimate; just as all other primitives the returned set of triples is not ensure to be complete

Listing 2. Graph pattern-based semantic template

?s a doap:Project; foaf:member ?o	This graph pattern queries all triples where the subject is of type doap:Project and where the same subject has triples indicating the members
?s ?p ?o. ?o a foaf:Person	This template matches all triples where the object is of type foaf:Person
?s foaf:name ?a; foaf:mbox ?b	This last template matches the triples that contain subjects for which the name and a mailbox (foaf:mbox) are indicated

1 means to match data in a Triple Space, analogue to tuple templates
2 in Linda.

3. Triple Space kernel

4 Like with the Web, the TSC project proposal aimed at building a
5 Triple Space Computing infrastructure based on the abstract model
6 called REST (Representational State Transfer) (Fielding, 2000). The
7 fundamental principle of REST is that resources are identified by URIs
8 and accessed via a stateless protocol like HTTP in order to transfer
9 representations, such as HTML or XML documents, of resources over
10 the network. HTTP provides a minimal set of operations enough to
11 model any applications domain (Fielding, 2000).

12 Since every representation transfer must be initiated by the client,
13 and every response must be generated as soon as possible (the
14 statelessness requirement) there is no way for a server to transmit
15 any information to a client asynchronously in REST. Furthermore,
16 there is no direct way to model a peer-to-peer relationship (Khare,
17 Taylor, 2004) between clients. Finally, HTTP caching based on expira-
18 tion times for cached requests is not applicable in TSC; where a
19 server has no pre-knowledge of the lifetimes of named graphs. The
20 limitations of REST in the context of TSC motivated our approach of
21 a hybrid architecture called super-peer architecture, which combines
22 traditional client/server and peer-to-peer architectures. In this archi-
23 tecture there are three kinds of nodes: servers, heavy clients and
24 light clients. In the simplest configuration, a particular Triple Space is

realized by a single server, which is accessed by multiple light clients, 25
for example via HTTP, in order to write and read named graphs and 26
to receive notifications about graphs of interest. As the number of 27
light clients increases, the server may become a bottleneck. To over- 28
come this, additional servers can be deployed to provide additional 29
access points to a Triple Space for light clients. As a result, a single 30
Triple Space is be effectively spanned by multiple servers, which use 31
an inter-server protocol to consistently distribute and collect named 32
graphs to and from other involved servers. Servers can also be de- 33
ployed to act as caching proxies in order to improve clients-perceived 34
access times. The third kind of nodes is heavy clients, which are not 35

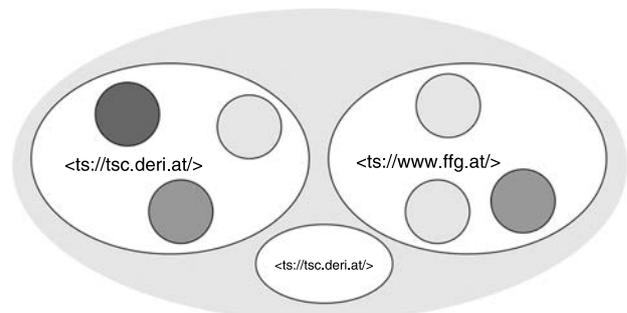


Fig. 1. Definition of the Triple Space

1 always connected to the system. Like servers they are capable to
 2 store and replicate Triple Spaces and support users and applications
 3 to work off-line with their own replicas. While heavy clients can
 4 join existing Triple Spaces spanned by servers, they are not forced
 5 to do so.

6 The core functionality of TSC servers and heavy clients is realized
 7 by a component called Triple Space kernel (TS kernel). Heavy clients
 8 run in the same address space as the TS kernel, and the TS kernel is
 9 accessed by its native interface. Light clients use proxies to access
 10 the TS kernel of a server node transparently over the network. As a
 11 variation a light client can access a TS kernel via a standardized
 12 protocol like HTTP, as already mentioned above. In this case a server
 13 side component, e.g. a servlet, translates the protocol to the native
 14 TS kernel interface. Figure 2 shows the architecture of the TS kernel.
 15 Main components of the TS kernel will be briefly described in sub-
 16 sections below.

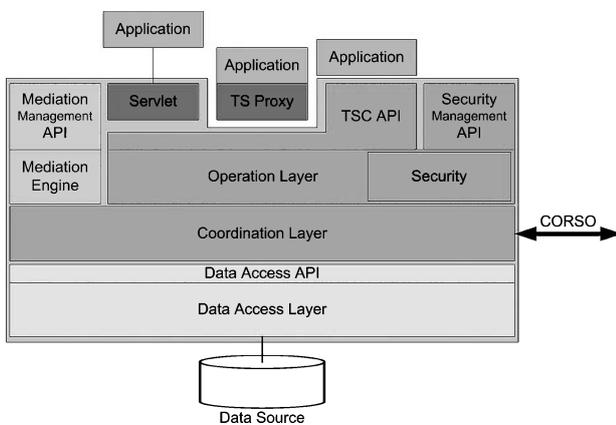


Fig. 2. Triple Space kernel architecture

17 **3.1 Mediation engine**

18 Due to diversity in the nature of different communicating partici-
 19 pants over Triple Space, the possibility of the heterogeneity in the
 20 data used for communication of different participants may arise and
 21 make mediation an important issue to be resolved in the Triple Space
 22 Computing. The Mediation Engine (*Shafiq et al., 2006b*) as part of
 23 the TS kernel (*Riemer et al., 2007*) is concerned with handling this
 24 heterogeneity by resolving possibly occurring mismatches among
 25 different triples. Assume two TSC participants using different data
 26 models for communication. Then an RDF instance in an RDF schema
 27 of one TSC participant is needed to be represented in the RDF
 28 schema of the other TSC participant without altering or loosing the
 29 semantics. For this reason, a mapping language is needed that
 30 specifies how to transform the RDF triples according to different
 31 RDF Schemas of different communicating participants. The media-
 32 tion rules are to be specified at design time and will be processed by
 33 a mediation engine at runtime.

34 The TSC mediation engine starts working when users add media-
 35 tion mapping rules via mediation management interface. Rules
 36 are defined in the Abstract Mapping Language (AML) (*Scharffe,
 37 de Bruijn, 2005*) which is independent of any programming lan-
 38 guage and is able to model complex correspondences that may
 39 stand between two ontologies. Graphical user interfaces are avail-
 40 able to define rules in AML. In TSC mediation rules are themselves
 41 stored in Triple Spaces as RDF graphs. As a result, rules created
 42 at one server or heavy client can be shared with all other nodes
 43 spanning a Triple Space. To represent mediation rules in RDF, an
 44 RDF grounding for AML was defined. A component called mediation

manager implements serialization of rules and helps adding, repla- 45
 cing and deleting mapping rules. 46

3.2 Coordination layer 47

The coordination layer has three responsibilities, (1) local TS opera- 48
 tions, such as reading and writing named graphs are executed by 49
 accessing the local data access layer and by consistently propagating 50
 changes to other involved TS kernels, (2) changes of a space origi- 51
 nating from other TS kernels are recognized and applied to the local 52
 data access layer, and (3) remote TS kernels involved to span a 53
 certain space are discovered automatically in the network. 54

Consistent concurrent access to named graphs is provided via 55
 transactions. In principle both optimistic and pessimistic transac- 56
 tions are applicable for TSC; however, they are not exchangeable 57
 due to differences in their semantics. We decided to support optimistic 58
 transactions, because they provide a higher degree of concurrency, 59
 if read operations are more frequent than write operations, which 60
 results in a higher throughput, because they are free of deadlocks 61
 without the introduction of additional, semantically sophisticated 62
 timeout parameters and finally, because they enable a pragmatic 63
 integration of a data access layer, which itself does not support a 64
 transaction interface. 65

The prototype implementation of the coordination layer is based 66
 on the CORSO (Coordinated Shared Objects Spaces) (*Kühn, 1994*) 67
 middleware. CORSO is a peer-to-peer implementation of a virtual 68
 shared data space, which allows reading and writing structured, 69
 shared data objects. It has a built-in distributed transaction manager 70
 and distributes spaces via an asynchronous, primary-based replica- 71
 tion protocol. In the TSC prototype, Triple Spaces and named graphs 72
 are mapped to distributed CORSO data structures. TSC operations 73
 like reading and writing named graphs are translated to algorithms 74
 on these CORSO data structures. CORSO further provides a notifica- 75
 tion mechanism to get informed about changes in the shared space. 76
 The coordination layer uses CORSO notifications to react on inserted 77
 or removed named graphs and to asynchronously update the under- 78
 lying data access layer. The discovery of TS kernels involved in 79
 spanning a Triple Space is based on the Domain Name System 80
 (DNS) for wide area networks and on a new protocol based on 81
 UDP-multicast and CORSO for local area networks. 82

3.3 Data access layer 83

Any Triple Space implementation requires a storage and retrieval 84
 framework to (1) ensure the desired persistency, (2) to support se- 85
 mantic template matching based on Semantic Web query languages 86
 and (3) to provide at least a limited amount of reasoning. In order to 87
 bind arbitrary data stores and query engines to TS kernels we define 88
 a Data Access Layer (DAL) which defines operations for storing, 89
 retrieving and deleting RDF graphs. 90

The prototype implementation of the data access layer is based on 91
 YARS (Yet Another RDF Store) (*Harth, Decker, 2005*), a lightweight 92
 persistence framework developed in Java at DERI Galway which uses 93
 optimized indexes for better query performance. Besides the note- 94
 worthy performance, the fact that the consortium has access to the 95
 source code and the implementers through DERI Innsbruck, YARS 96
 has in particular be chosen as it is constructed to store quads or 97
 contextualized triples instead of plain RDF triples. This allows for 98
 direct usage of the chosen data model based on named graphs 99
 (*Carroll et al., 2005*). 100

One of the main tasks of the data access layer is to translate 101
 templates into N3QL queries for YARS. To keep the Data Access 102
 API (DAPI) as simple as possible it only defines one operations to 103
 retrieve data: retrieve(URI ts, Transaction tx, Template t):Graph. The 104
 TSC API, however, allows a space user to retrieve data either based 105
 on templates or by use of the graph name. As the DAPI does not 106

1 directly support an interface for URI-based retrieval it is also neces-
 2 sary to adapt the operation layer in order to transform those
 3 requests into templates. First, the URI has to be packed into a graph
 4 pattern template according to (Riemer et al., 2006) as part of the
 5 Operation Layer processing. The request is then forwarded in form
 6 of the template to the DAL, where the template is transformed into
 7 a N3QL query that can be sent to the YARS servlet.

8 **4. Triple Space Computing for Semantic Web Services**

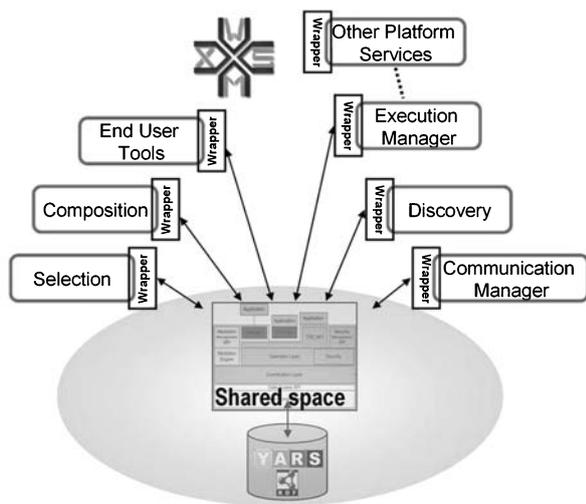
9 Semantic Web Services have been emerged to enable dynamic Web
 10 Service discovery, composition and execution by using semantic
 11 descriptions using ontologies as its basis. The Semantic Web Services
 12 framework has been envisioned (Fensel, Bussler, 2002). It pro-
 13 vides an ontology, called Web Service Modeling Ontology (WSMO)
 14 (Roman et al., 2006), a language, called Web Service Modeling
 15 Language (WSML) (Roman et al., 2006), which provides a formal
 16 syntax and semantics for WSMO, and an execution environment,
 17 called Web Service Execution Environment (WSMX) (Roman et al.,
 18 2006), which is a reference implementation for WSMO, offering
 19 support for interacting with SWS.

20 The currently used communication paradigm in Semantic Web
 21 Services (SWS) (Fensel, Bussler, 2002) is synchronous, i.e. users

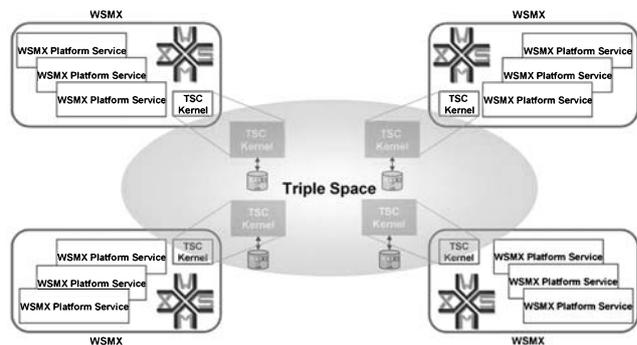
communicate with SWS and SWS communicate with real world
 Web Services by sending synchronous messages. The problem with
 synchronous communication is that it requires a quick response as
 it makes sender halt until the response is received, which is not
 possible in case of execution process in SWS as it involves heavy
 processing of semantic descriptions in terms of discovery, selection,
 composition, mediation, execution. This problem has been over-
 come by introducing Triple Space Computing as being semantic
 based asynchronous communication paradigm for communication
 and coordination of SWS. The Web Services Execution Environment
 (WSMX) is our reference implementation for SWS in which the Triple
 Space Computing middleware is being integrated. Using Triple
 Space Computing in WSMX enables to support greater modulariza-
 tion, flexibility and decoupling in communication and coordination
 and to be highly distributed and easily accessible. Multiple TS kernels
 coordinate with each other to form a virtual space that acts as
 underline middleware which is used for communication by reading
 and writing data.

The integration of WSMX and Triple Space Computing has
 been proposed in four major aspects (Shafiq et al., 2006a): (1)
 enabling component management in WSMX using Triple Space
 Computing, (2) allowing external communication grounding in

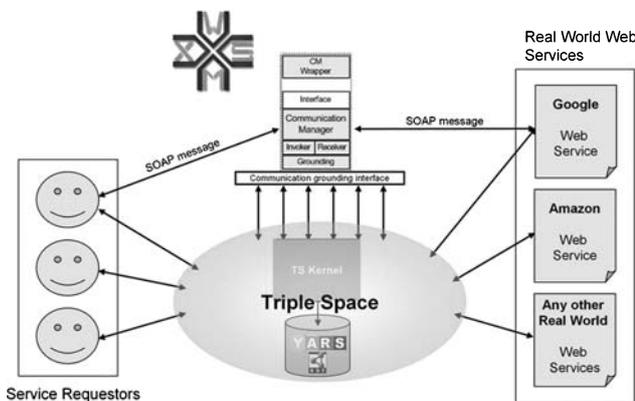
1) Components Management



2) Inter-WSMX Communication and Coordination



3) External Communication Grounding



4) Resource Management

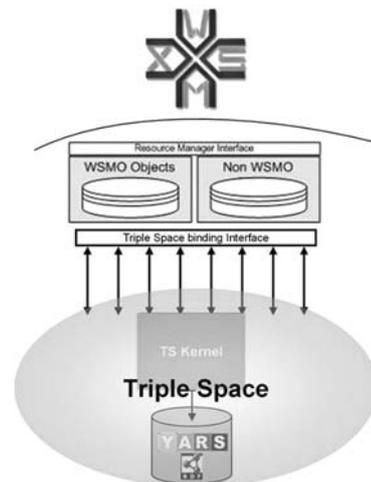


Fig. 3. Triple Space Computing for WSMX

1 WSMX, (3) providing resource management, and (4) enabling communication and coordination between different inter-connected
2 WSMX systems. Each of the integration aspect is described in the
3 subsections below. In summary, Triple Space Computing acts as a
4 middleware for WSMX, Web Services, different other Semantic Web
5 applications, and users to communicate with each other. Figure 3
6 shows an initial architecture of each integration aspect.

8 4.1 Component management in WSMX using Triple Space 9 Computing

10 WSMX has a management component that manages the over all
11 execution of the system by coordinating different components based
12 on dynamic execution semantics. In this way there has been made a
13 clear separation between business and management logic in WSMX.
14 The individual components have clearly defined interfaces and have
15 component implementation well separated with communication
16 issues. Each component in WSMX has a wrapper to handle the
17 communication issues. The WSMX manager and individual compo-
18 nents wrappers are needed to be interfaced with Triple Space in
19 order to enable the WSMX manager to manage the components
20 over Triple Space. The communication between manager and wrap-
21 pers of the components will be carried out by publishing and
22 subscribing the data as a set of RDF graphs over triple space.
23 The wrappers of components that handle communication will be inter-
24 faced with Triple Space middleware. The WSMX manager has been
25 designed in such a way that it could distinguish between the data
26 flows related with the business logic (execution of components based
27 on the requirements of a concrete operational semantic) and the
28 data flows related with the management logic (monitoring the com-
29 ponents, load-balancing, instantiation of threads, etc.).

30 There are two ways for WSMX components to access a TS core,
31 i.e. heavy clients embed the TS core as a Java package and the
32 application and TS core run in the same Java Virtual Machine. In
33 this case CORSO (Kühn, 1994) and YARS (Harth, Decker, 2005)
34 runtimes need to be deployed together with the heavy client ap-
35 plication. The second way is to deploy a standalone TS kernel as a
36 server, which may be accessed by multiple light clients via remoting.
37 Both scenarios can work. However, we recommend using light
38 clients in case of communication and coordination within the WSMX
39 system as in such case it will make the keep the complexity level of
40 components wrapper and the access of light client embedded in
41 wrappers will be local to the Triple Space kernel.

42 4.2 Multiple WSMX instances interconnection using Triple 43 Space Computing

44 After enabling WSMX Manager to perform communication and
45 coordination of components internally, the next step will be to
46 enable the communication and coordination of different WSMXs
47 over Triple Space, i.e. forming a cluster of different interconnected
48 WSMX nodes to support distributed service discovery, selection, com-
49 position, mediation, invocation, etc. The communication model used
50 in the current implementation of WSMX is synchronous. Synchronous
51 communication is beneficial when immediate responses are re-
52 quired. Since WSMX is dealing with Web service Discovery, Media-
53 tion and Invocation, immediate responses are usually not available.
54 In such situations, the synchronous communication will be costly as
55 it forces the system (component) to remain idle until the response is
56 available. In order to minimize such overhead imposed by synchrony,
57 Triple Space can serve as a communication channel between
58 WSMXs thereby introducing synchronicity between communicating
59 parties. The Triple Space supports purely asynchronous communica-
60 tion that optimizes performance as well as communication robustness.

61 The figure above shows the idea of having different WSMX systems
62 to be interconnected to each other over Triple Space. This will help

the WSMX in providing distributed service discovery, selection, com-
position, mediation and invocation. There can be the possibility that
different WSMX systems are running at different location over the
globe containing different information (i.e. semantic description of
commercial Web Services, mediation rules, ontologies and goals).
The service requestor local to a particular WSMX will not be aware
of other WSMX systems and the data contained by other WSMX
systems. In this case, it will enable different WSMX systems to be
aware of each other and to access the data of other WSMXs over
Triple Space, or redirect the goals to other WSMXs.

4.3 External communication grounding in WSMX using Triple Space Computing

WSMX acts as a semantic middleware between users and real world
Web Services. Currently, due to existence of message oriented
communication paradigm, users communicate with WSMX and
WSMX communicate with Web Services synchronously. The external
communication manager of WSMX is needed to provide a support
to communicate over Triple Space. The interfaces for sending and
receiving external messages by WSMX are needed to provide a
grounding support to alternatively communicate over Triple Space.
This needs to be resolved by addressing several issues, i.e. invoker
component in WSMX is needed to support Web Services Description
Language (WSDL) and Simple Object Access Protocol (SOAP) com-
munication binding over Triple Space. The Entry point interfaces will
be interfaced with Triple Space middleware in order to provide the
glue between existing Web Services standards and Triple Space
Computing.

The Communication Manager will be provided with Triple Space
based grounding support. It will help in providing an additional or
alternative Triple Space based access interface to access WSMX. It
will enable Triple Space clients to submit Goals to WSMX via Triple
Space which will bring the real sense of asynchronous communica-
tion of Triple Space because normally Goal execution in WSMX
(performing service discovery, selection, composition, mediation and
invocation) takes significant amount of time. When the service
requestors will be able to submit the Goals to WSMX over Triple
Space, it will not make them hang-up with WSMX until the Goal has
been executed and will make the communication process of users
with WSMX more flexible and reliable.

4.4 Resource management in WSMX using Triple Space Computing

WSMX contains different repositories to store ontologies, goals,
mediators and Web Services descriptions as WSML based files. The
internal repositories of WSMX are needed to be made optional and
enable to store the WSML based data as set of RDF named graphs in
Triple Space Storage. This is mainly concerned with transforming the
existing representation of data in form of WSML into RDF represen-
tation. The repository interfaces are needed to be interfaced with
Triple Space middleware. The Resource Manager in WSMX currently
manages the persistent storage of data in the repositories. The
Resource Manager provides a heterogeneous interface for WSMX.
The component implementing this interface is responsible for storing
every data item WSMX uses. The WSMO API provides a set of Java
interfaces that can be used to represent the domain model defined
by WSMO. WSMO4J (<http://wsmo4j.sourceforge.net>) provides
both the API itself and a reference implementation. Currently WSMX
defines interfaces for six repositories. Four of these repositories
correspond to the top level concept of WSMO, i.e. Web Services,
ontologies, goals, and mediators. The fifth repository is for non-
WSMO data items e.g. events and messages. Finally, the sixth repo-
sitory stores WSDL documents used to ground WSMO service
descriptions to SOAP.

1 The storage of WSMO top level entities on Triple Space will help in
 2 enhancing and fastening the process access of the data items after-
 3 wards. For instance, in the current discovery mechanism of WSMX,
 4 the WSML reasoners have to reason on each and every Web Service
 5 description available in the local repositories which takes significant
 6 amount of time. When the Web Services descriptions will be stored
 7 over Triple Space, the template matching based simpler reasoning
 8 will be used as a first step in order to filter-out the most relevant and
 9 possibly required Web Service descriptions. The filtered Web Services
 10 descriptions based on template based matching over Triple Space
 11 are retrieved and converted back to WSML to be used by WSML
 12 reasoners. It makes the process of discovery simpler and faster by
 13 performing reasoning operations only on relevant Web Service
 14 descriptions rather than all.

15 5. Conclusions

16 In this paper we provide an overview of overall work in-progress in
 17 Triple Space Computing (TSC) project funded by the Austrian Gov-
 18 ernment under the program FIT-IT Semantic System. In the project
 19 we are building the Triple Space Computing as a communication
 20 and coordination framework for semantic technologies. In this paper
 21 we presented the background of TSC, introduction, state-of-the-art,
 22 TSC framework, data and interaction model, TSC architecture and
 23 TSC integration with Semantic Web Services. The project has en-
 24 tered into its final phase where theoretical work has been completed
 25 and currently prototypes are under development which will be fol-
 26 lowed by extensive evaluation.

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